## A MARKERLESS AUGMENTED REALITY ENVIRONMENT FOR MEDICAL DATA VISUALIZATION

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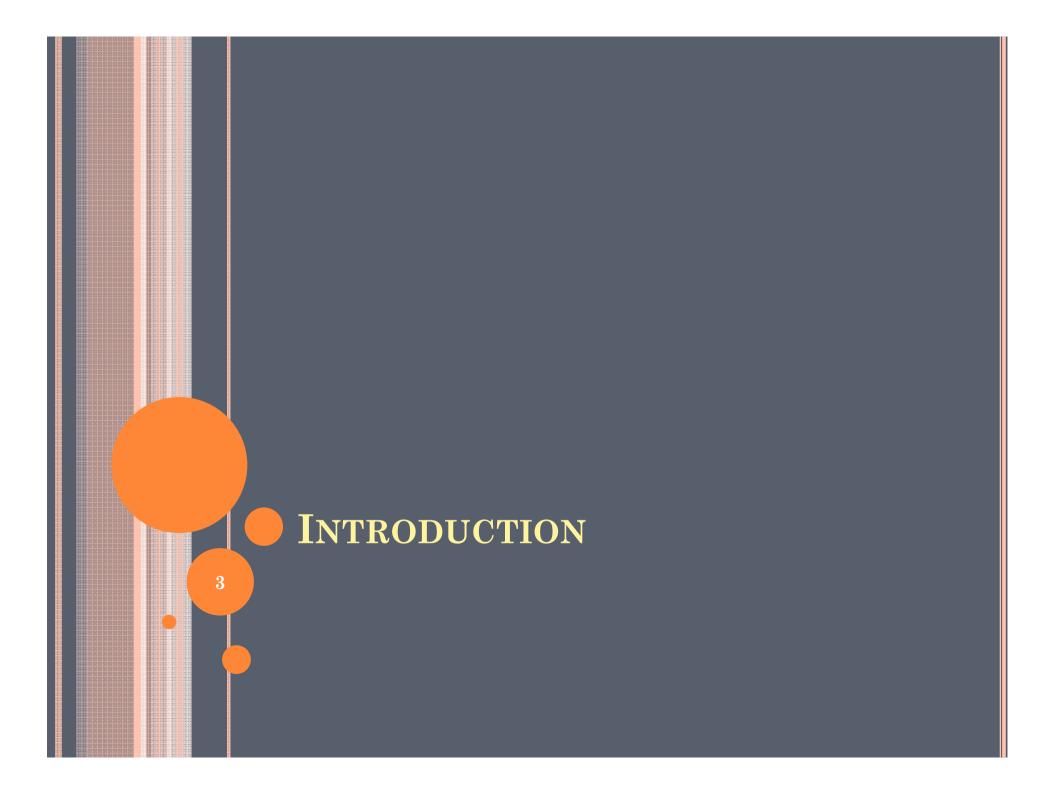
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## AGENDA

• Introduction;

- Technique Overview;
- Medical Volume Rendering;
- Results and Discussion;
- Conclusions and Future Work;

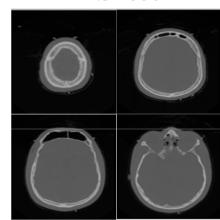


#### CONTEXT

#### • Problem: On-Patient Medical Data Visualization 2D Slices "Patient"

3D Data





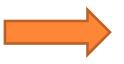
which must be composed on

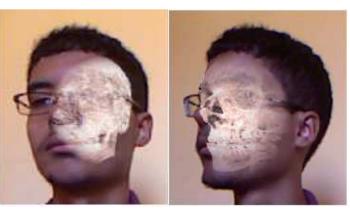


• Solution: Augmented Reality

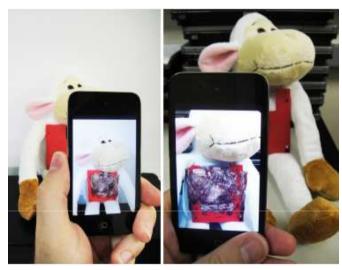


F+C Visualization

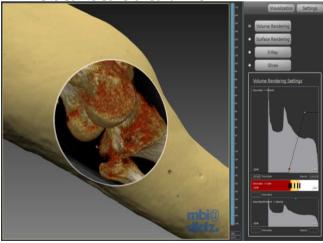




#### CURRENT SCENARIO



#### <u>Debarba et al. 2012</u>



Maier-Hein et al. 2011



Kutter et al. 2008



Lee et al. 2012

#### CONTRIBUTION

- Our main contribution is the proposition of a real-time markerless AR solution with support to:
  - On-Patient Medical Data Visualization by Volume Rendering;
  - Non-Rigid Registration;
  - Low-Cost Hardware Components;
- Motivation: Surgery simulation and prediction by craniofacial specialists;

## **TECHNIQUE OVERVIEW**

### COMPUTATIONAL INFRASTRUCTURE ENVIRONMENT

# • The computational infrastructure requires two RGB-D sensors and an AR glasses;

Architecture

## Augmented Reality Glasses Observer Kinect Kinect Observed Observed

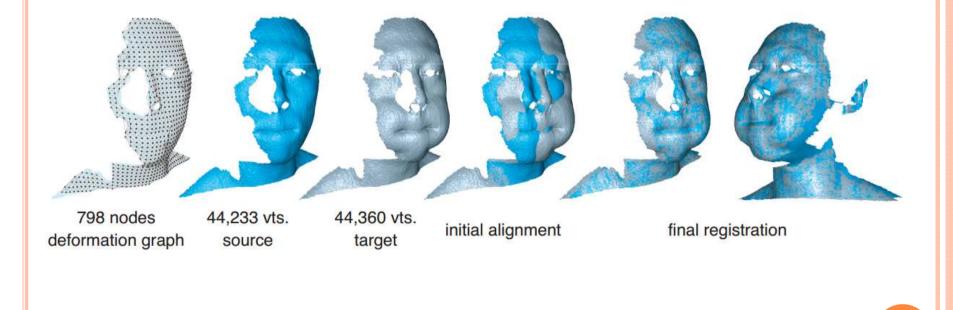
#### MARKERLESS TRACKING

• Markerless tracking is done based on a 3D reference model reconstructed from the patient's region of interest.



#### DEFORMATION MODEL

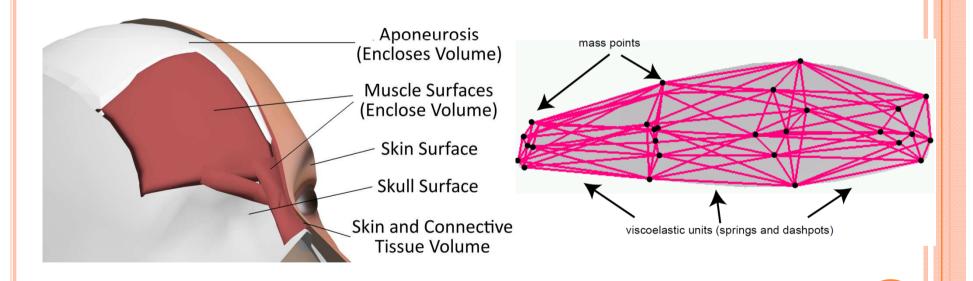
• Fast non-rigid registration is done by building a graph on the 3D reference model.



Li et al. 2009. Global Correspondence Optimization for Non-Rigid Registration of Depth Scans

#### SOFT TISSUE DEFORMATION

• For surgery simulation, patient's soft tissue deformation can be simulated by using Mass Spring models.

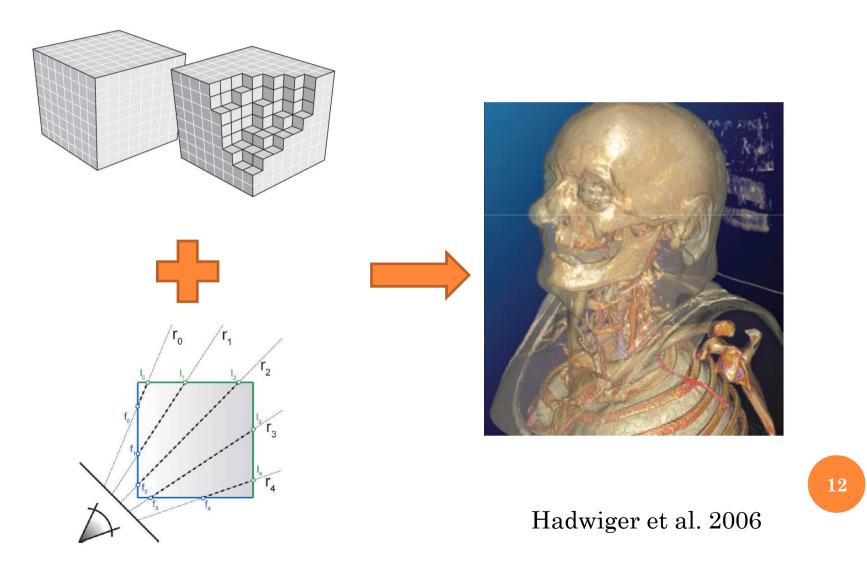


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Warburton e Maddock (2013). Creating Finite Element Models of Facial Soft Tissue

Victor Ng-Thow-Hing (2001). Anatomically-Based Models for Physical and Geometric Reconstruction of Humans and Other Animals

#### MEDICAL VOLUME RENDERING



#### • To improve image quality:

• Stochastic Jittering;

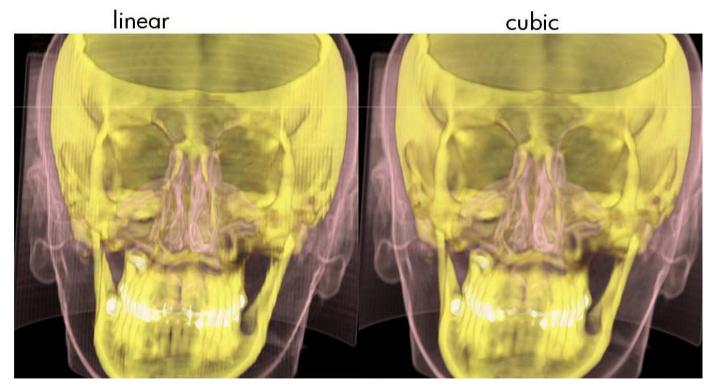




Hadwiger et al. 2006

#### • To improve image quality:

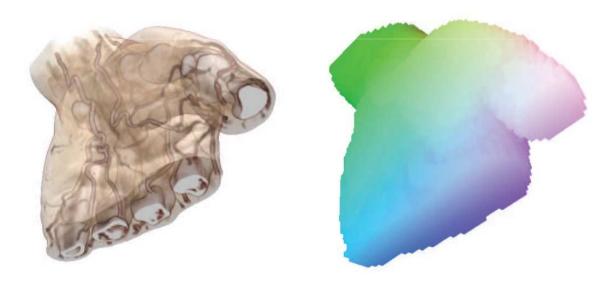
• Tricubic Interpolation;



Hadwiger et al. 2006

• To improve performance:

• Empty-Space Skipping of Non-Visible Voxels;

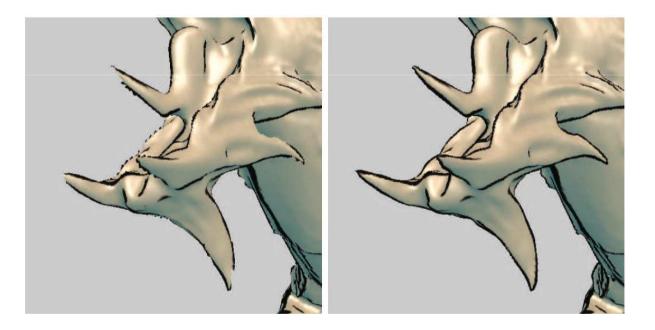


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Hadwiger et al. 2009

#### • To improve performance:

• Adaptive Sampling;



#### Hadwiger et al. 2009

- Additional features:
  - Pre-integrated Transfer Functions;



#### • Additional features:

- Pre-integrated Transfer Functions;
- Blinn-Phong shading;



#### • Additional features:

- Pre-integrated Transfer Functions;
- Blinn-Phong shading;
- Non-polygonal iso-surface rendering;



#### INTEGRATION INTO A MAR ENVIRONMENT

• Blending:

$$I_{\text{final}} = \beta * I_{\text{real}} + (1 - \beta) * I_{\text{medical}}$$

- The contribution of each image (ß per pixel) is dynamically defined by using focus + context visualization;
- To solve occlusion, the depth maps of the 3D reference object reconstructed previously and the 3D object coming from the sensor's live stream are compared.



#### EXPERIMENTAL SETUP

- The evaluation of the proposed approach is conducted in a scenario where the patient's head is augmented with a generic CT volumetric dataset of a head;
- The deformation model presented is evaluated in terms of performance and accuracy in a real situation;
- The medical dataset used is the CT volumetric data of the Visible Male's head of resolution 128 x 256 x 256;

- The 3D reference model reconstruction runs in 30 FPS;
- The on-patient medical data focus + context visualization based on markerless tracking runs in 20 FPS;



# • Focus+context visualization enhances the human perception of the scene;

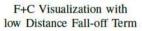
Naive F+C Visualization





F+C Visualization with

low Curvature Term



F+C Visualization with high Curvature Term



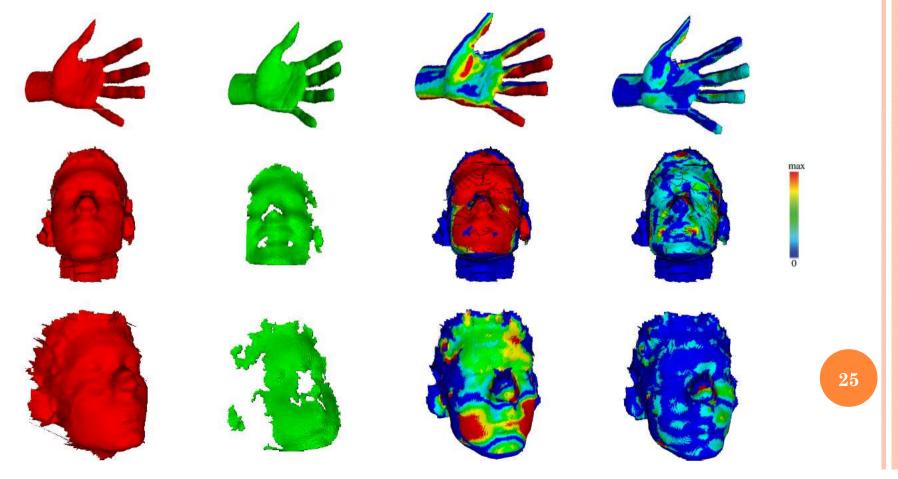
F+C Visualization with high Distance Fall-off Term







• The deformation model was tested on a typical dataset captured by the Kinect sensor.



- The computational infrastructure is almost finished. Currently, it has been integrated with the on-patient medical data visualization;
- Soft tissue deformation is not incorporated yet into our computational system. However, the first simulations show encouraging results.

## **CONCLUSIONS AND FUTURE** WORK

#### CONCLUSIONS

- We have presented a multiview, marker-free augmented reality approach for on-patient volumetric medical data visualization;
- Markerless tracking runs in real-time;
- An algorithm for fast non-rigid registration of surfaces using GPU was presented;

#### FUTURE WORK

Improve realism by illumination;
Multi-frame non-rigid registration;
Accuracy validation;

#### ACKNOWLEDGMENTS

• We would like to acknowledge the support of FAPESB, CAPES and CNPq for this work. Also, we are grateful to the PCL project for providing the open-source implementation of the KinectFusion algorithm.

# Thank you!

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